



Die Ressourcenuniversität. Seit 1765.

Institut für Numerische Mathematik und Optimierung



# Covariance Eigenproblems and their Numerical Treatment

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(joint work with Ingolf Busch)

AMCS Seminar, KAUST  
September 26, 2012



... where again?



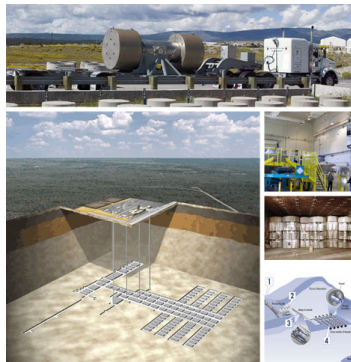
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# PDEs with Random Data

## Typical UQ Application: Radioactive Waste Repository Site Assessment

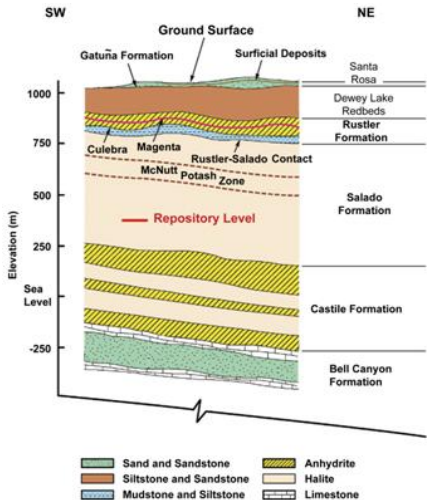
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Carlsbad, NM
- Groundwater transport of radionuclides
- Uncertainty in hydraulic conductivity
- Quantity of interest: travel time
- **Approach:** Model uncertainty (lack of knowledge) stochastically. Propagate random input data to travel time.
- Requires solution of PDE with random data + post-processing.



# PDEs with Random Data

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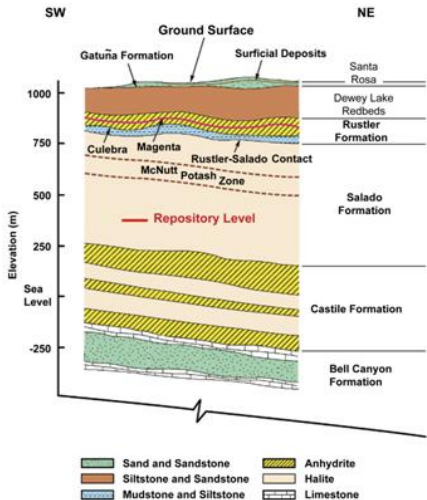
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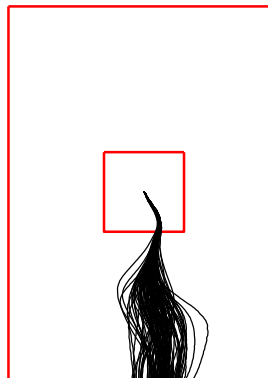
# PDEs with Random Data

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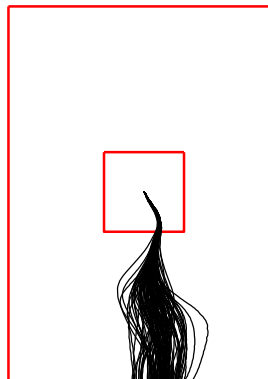
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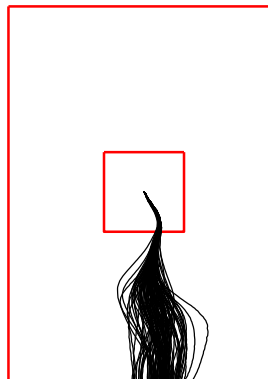


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- 1 Expansions of Random Fields
  - Random Fields and Covariance
  - RKHS
  - Karhunen-Loève Expansion
- 2 Numerical Approximation
  - Galerkin Discretization
  - Adapted Quadrature
  - Lanczos Eigenpair Approximation
  - Hierarchical Matrix Approximation
- 3 Numerical Examples

## ① Expansions of Random Fields

Random Fields and Covariance

RKHS

Karhunen-Loève Expansion

## ② Numerical Approximation

Galerkin Discretization

Adapted Quadrature

Lanczos Eigenpair Approximation

Hierarchical Matrix Approximation

## ③ Numerical Examples

**Given:** compact domain  $D \subset \mathbb{R}^d$ , probability space  $(\Omega, \mathfrak{A}, \mathbf{P})$ .

A real-valued **random field** (RF)

$$a : D \times \Omega \rightarrow \mathbb{R}$$

is a stochastic process whose index variable is a spatial coordinate.

Thus, for each  $\mathbf{x} \in D$ ,

$a(\mathbf{x}, \cdot)$  is a random variable (RV).

**Alternatively:** for each  $\omega \in \Omega$ ,

$a(\cdot, \omega)$  is a random function defined on  $D$ .

**Second-order RF:**  $a(\mathbf{x}, \cdot) \in L^2_{\mathbf{P}}(\Omega) = L^2(\Omega, \mathfrak{A}, \mathbf{P})$  for all  $\mathbf{x} \in D$ .

**Mean** of RF at  $\mathbf{x} \in D$ :

$$\bar{a}(\mathbf{x}) := \mathbf{E} [a(\mathbf{x}, \cdot)].$$

**Covariance** of RF at  $\mathbf{x}, \mathbf{y} \in D$ :

$$\begin{aligned} c(\mathbf{x}, \mathbf{y}) &:= \text{Cov}(a(\mathbf{x}, \cdot), a(\mathbf{y}, \cdot)) \\ &= \mathbf{E} [(a(\mathbf{x}, \cdot) - \bar{a}(\mathbf{x})) (a(\mathbf{y}, \cdot) - \bar{a}(\mathbf{y}))] \end{aligned}$$

For  $\tilde{a} := a - \bar{a}$ , we have  $\mathbf{E} [\tilde{a}] = 0$  (**centered RF**).

Moreover, for any selection  $\alpha_1, \dots, \alpha_n \in \mathbb{R}$  and  $\mathbf{x}_1, \dots, \mathbf{x}_n \in D$ ,

$$0 \leq \text{Var} \left( \sum_{i=1}^n \alpha_i a(\mathbf{x}_i, \cdot) \right) = \sum_{i,j=1}^n \alpha_i \alpha_j c(\mathbf{x}_i, \mathbf{x}_j),$$

i.e., covariance functions are **positive definite**. This is also sufficient for  $c(\mathbf{x}, \mathbf{y})$  to be the covariance function of a second-order RF.

**Note:** if a covariance function  $c : D \times D \rightarrow \mathbb{R}$  is continuous along the **diagonal set**  $\{(\mathbf{x}, \mathbf{x}) : \mathbf{x} \in D\}$ , then it is continuous on all of  $D \times D$ .

- Translation invariance:

$$c(\mathbf{x}, \mathbf{y}) = c(\mathbf{x} - \mathbf{y})$$

(RF **stationary, homogeneous**).

- Rotation invariant:

$$c(\mathbf{x}, \mathbf{y}) = c(\|\mathbf{x} - \mathbf{y}\|)$$

(RF **isotropic**).

- RF **Gaussian**: each finite collection  $\{a(\mathbf{x}_i, \cdot)\}_{i=1}^n$  has multivariate Gaussian distribution.
- For now: assume RF Gaussian, centered, with strictly positive definite, continuous covariance function.

**Goal:** Representation of second-order centered Gaussian RF as

$$a(\mathbf{x}, \omega) = \sum_{j=1}^{\infty} \xi_j(\omega) a_j(\mathbf{x}), \quad \xi_j \in L^2(\Omega, \mathfrak{A}, \mathbf{P}),$$

$a_j : D \rightarrow \mathbb{R}$  suitable functions.

**Convenient Setting:** Introduce separable Hilbert space structure.

Set

$$\mathcal{S} := \left\{ f : D \rightarrow \mathbb{R} : f(\cdot) = \sum_{j=1}^n \alpha_j c(\mathbf{x}_j, \cdot), \alpha_j \in \mathbb{R}, \mathbf{x}_i \in D, n \in \mathbb{N} \right\}$$

with inner product (note  $c(\cdot, \cdot)$  strictly pos. def.)

$$(f, g) = \left( \sum_{i=1}^n \alpha_i c(\mathbf{x}_i, \cdot), \sum_{j=1}^m \beta_j c(\mathbf{x}_j, \cdot) \right) := \sum_{i=1}^n \sum_{j=1}^m \alpha_i \beta_j c(\mathbf{x}_i, \mathbf{x}_j).$$



This inner product on  $\mathcal{S}$  has **reproducing kernel property** w.r.t.  $c$ :

$$(f, c(\mathbf{y}, \cdot)) = \left( \sum_{i=1}^n \alpha_i c(\mathbf{x}_i, \cdot), c(\mathbf{y}, \cdot) \right) = \sum_{i=1}^n \alpha_i c(\mathbf{x}_i, \mathbf{y}) = f(\mathbf{y}). \quad (*)$$

For sequence  $\{f_n\}_{n \in \mathbb{N}}$  in  $\mathcal{S}$ , if  $\|\cdot\|$  denotes associated norm,

$$\begin{aligned} |f_n(\mathbf{x}) - f_m(\mathbf{x})| &= |(f_n - f_m, c(\mathbf{x}, \cdot))| \\ &\leq \|f_n - f_m\| \|c(\mathbf{x}, \cdot)\| = \|f_n - f_m\| c(\mathbf{x}, \mathbf{x}), \end{aligned}$$

i.e.,  $\{f_n\}$  Cauchy in  $\|\cdot\| \Rightarrow \{f_n\}$  Cauchy pointwise.

Define **reproducing kernel Hilbert space (RKHS)**  $\mathcal{H}_c$  of  $c$  (or  $a$ ) as closure of  $\mathcal{S}$  w.r.t.  $\|\cdot\|$ . Reproducing property  $(*)$  for all  $f \in \mathcal{H}_c$  follows from separability of compact set  $D$ .

Hilbert space  $\mathcal{H}$  of functions  $f : D \rightarrow \mathbb{R}$ ,  $D \subset \mathbb{R}^d$ , for which all evaluation functionals

$$\delta_{\mathbf{x}} : \mathcal{H} \rightarrow \mathbb{R}, \quad \langle \delta_{\mathbf{x}}, f \rangle = f(\mathbf{x}), \quad \forall \mathbf{x} \in D, f \in \mathcal{H}.$$

are continuous.

Reproducing kernel  $k : D \times D \rightarrow \mathbb{R}$  such that  $k(\mathbf{x}, \cdot) \in \mathcal{H}$  and

$$(f, k(\mathbf{x}, \cdot)) = f(\mathbf{x}) \quad \forall f \in \mathcal{H}, \forall \mathbf{x} \in D$$

i.e.,  $k(\mathbf{x}, \cdot) = \delta_{\mathbf{x}}$ .

- Long history dating back to [Mercer, 1909], [Aronsojn, 1944].
- Popularized as setting for optimal prediction/estimation of time series by E. Parzen in the 1960s.
- Recent monograph [Berlinet & Thomas-Agnan, 2007].
- Generalizations to Hilbert spaces of distributions [Meidan, 1979], [Bogachev, 1998]

For  $\mathcal{V} := \text{span}\{a(\mathbf{x}, \cdot) : \mathbf{x} \in D\} \subset L^2_{\mathbb{P}}(\Omega)$ , define linear mapping

$$\Xi : \mathcal{S} \rightarrow \mathcal{V}$$

$$f = \sum_{j=1}^n \alpha_j c(\mathbf{x}_j, \cdot) \mapsto \sum_{j=1}^n \alpha_j a(\mathbf{x}_j, \cdot).$$

Clearly:  $\Xi(f)$  Gaussian  $\forall f \in \mathcal{S}$  and

$$(f, g) = (\Xi(f), \Xi(g))_{L^2_{\mathbb{P}}(\Omega)} \quad \forall f, g \in \mathcal{S}.$$

Extend  $\Xi$  to all of  $\mathcal{H}_c$ :

- range equal to all of  $\mathcal{V}$
- limits again Gaussian

**Canonical isomorphism** between the RKHS and the space of RV associated with RF  $a$ .

$\mathcal{H}_c$  separable, therefore  $\mathcal{V}$  separable.

Orthonormal (ON) basis  $\{f_n\}_{n \in \mathbb{N}}$  of  $\mathcal{H}_c$  yields ON basis

$$\xi_n := \Xi(f_n), \quad n \in \mathbb{N}$$

of  $\mathcal{V}$  where  $\xi_n \sim N(0, 1)$ .

ON expansion in  $\mathcal{V} \subset L_{\mathbf{P}}^2(\Omega)$ :

$$a(\mathbf{x}, \cdot) = \sum_{n=1}^{\infty} \mathbf{E}[a(\mathbf{x}, \cdot)\xi_n] \xi_n.$$

Isometry property of  $\Xi$  and reproducing property yield

$$\mathbf{E}[a(\mathbf{x}, \cdot)\xi_n] = \left( c(\mathbf{x}, \cdot), f_n \right) = f_n(\mathbf{x}).$$

**Result:** given an ON basis  $\{f_n\}_{n \in \mathbb{N}}$  of  $\mathcal{H}_c$ , the RF  $a$  has the expansion

$$a(\mathbf{x}, \cdot) = \sum_{n=1}^{\infty} \xi_n f_n(\mathbf{x}), \quad \mathbf{x} \in D,$$

where  $\xi_n$  is a sequence of uncorrelated Gaussian RVs with unit variance given by  $\xi_n = \Xi(f_n)$ .

**Note:** If  $a$  has a.s. continuous realizations, then convergence is uniform on  $D$  with probability one.

**Karhunen-Loève expansion:** use scaled eigenfunctions of Fredholm integral operator with kernel function  $c(\mathbf{x}, \mathbf{y})$  as the ON basis  $\{f_n\}$ .

# Expansion of Random Fields

## Eigenfunction expansion

Denote by  $\{(v_m, \lambda_m)\}_{m \in \mathbb{N}}$  the sequence of eigenpairs of the (compact, selfadjoint) **covariance operator**

$$C : L^2(D) \rightarrow L^2(D), \quad (Cu)(\mathbf{x}) = \int_D u(\mathbf{y})c(\mathbf{x}, \mathbf{y}) d\mathbf{y}, \quad \mathbf{x} \in D,$$

with  $\|v_m\|_{L^2(D)} = 1 \forall n$ .

## Theorem (Mercer, 1909)

*The continuous covariance kernel  $c$  has the expansion*

$$c(\mathbf{x}, \mathbf{y}) = \sum_{n=1}^{\infty} \lambda_n v_n(\mathbf{x})v_n(\mathbf{y})$$

*which converges absolutely and uniformly on  $D \times D$ .*

# Expansion of Random Fields

## Karhunen-Loève expansion

Easy to prove:  $\{\sqrt{\lambda_n}v_n\}_{n \in \mathbb{N}}$  is a complete ON system of  $\mathcal{H}_c$ .  
Therefore

### Theorem (Karhunen, 1947; Loève, 1945)

A second-order Gaussian random field  $a : D \times \Omega \rightarrow \mathbb{R}$  with continuous covariance function  $c$  and mean field  $\bar{a}$  has the expansion

$$a(\mathbf{x}, \omega) = \bar{a}(\mathbf{x}) + \sum_{n=1}^{\infty} \xi_n(\omega) a_n(\mathbf{x})$$

with uncorrelated RVs  $\xi_n \sim N(0, 1)$  and the scaled eigenfunctions  $a_n(\mathbf{x}) = \sqrt{\lambda_n}v_n(\mathbf{x})$ . The convergence is in quadratic mean in  $L^2_{\mathbb{P}}(\Omega)$  and uniform on  $D$ .

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- Find  $(\lambda, u) \in \mathbb{R} \times L^2(D)$  such that

$$Cu = \lambda u, \quad \|u\|_{L^2(D)} = 1$$

- with covariance operator  $C : L^2(D) \rightarrow L^2(D)$  defined by

$$(Cu)(x) = \int_D c(\mathbf{x}, \mathbf{y})u(\mathbf{y}) d\mathbf{y}$$

- $c(\mathbf{x}, \mathbf{y})$  covariance function (kernel) of RF defined on  $D \subset \mathbb{R}^d$ .

- Variational Formulation: Find  $(\lambda, u) \in \mathbb{R} \times L^2(D)$ , such that

$$(Cu, v) = \lambda(u, v) \quad \forall v \in L^2(D),$$

$$(Cu, v) = \int_D \int_D u(\mathbf{y}) c(\mathbf{x}, \mathbf{y}) v(\mathbf{x}) d\mathbf{y} d\mathbf{x}$$

$$(u, v) = \int_D u(\mathbf{x}) v(\mathbf{x}) d\mathbf{x}$$

- Galerkin approximation on finite dimensional subspace

$$\mathcal{U}_N = \text{span}\{\phi_1, \phi_2, \dots, \phi_N\} \subset L^2(D)$$

e.g.:  $\mathcal{U}_N$  space of discontinuous piecewise polynomials on a FE triangulation of  $D$

- No inter-element continuity needed for conforming discretization, basis function have small support.

### Theorem (Todor, 2006)

Let  $\{\mathcal{T}_h\}_{h>0}$  be a family of admissible triangulations of  $D$  with meshwidth  $h$  and define  $S_h$  to be the space of discontinuous piecewise polynomials of degree  $p$  on  $\mathcal{T}_h$ .

Then for any  $s > 0$  there exists a constant  $K = K(C, \mathcal{T}, p, s) > 0$  such that the Galerkin approximations  $\lambda_m^{(h)}$  of the eigenvalues  $\lambda_m$  of the covariance operator  $C$  satisfy

$$0 \leq \lambda_m - \lambda_m^{(h)} \leq K(h^{2p+2}\lambda_m^{1-s} + h^{4p+4}\lambda_m^{-2s}) \quad \forall m \in \mathbb{N}, \forall h > 0,$$

implying

$$0 \leq \lambda_m - \lambda_m^{(h)} \leq Kh^{2p+2}\lambda_m^{\frac{1}{2}-s} \quad \forall m \in \mathbb{N}, \forall h > 0.$$

# Covariance Eigenvalue Problem

## Generalized eigenvalue problem

- Coefficient vector  $\mathbf{u} \in \mathbb{R}^N$  for  $u = \sum_{j=1}^N u_j \phi_j$
- Galerkin projection leads to generalized eigenvalue problem

$$\mathbf{C}\mathbf{u} = \lambda\mathbf{M}\mathbf{u}$$

where

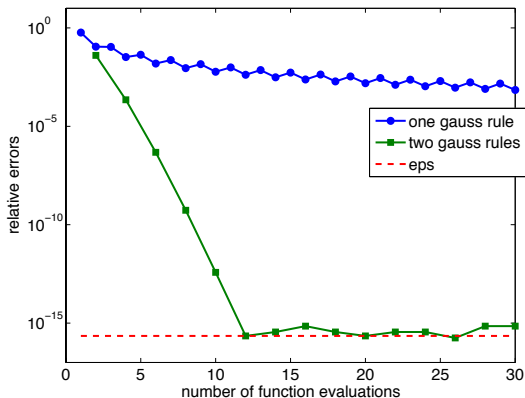
$$\begin{aligned} [\mathbf{C}]_{i,j} &= (C\phi_j, \phi_i) && \text{(discrete integral operator)} \\ [\mathbf{M}]_{i,j} &= (\phi_j, \phi_i) && \text{(mass matrix of basis)} \\ & i, j = 1, \dots, N. \end{aligned}$$

- $\mathbf{M}$  can be made diagonal (orthogonalize basis elementwise), but  $\mathbf{C}$  is in general **full**.

# Adapted Quadrature

## Quadrature of non smooth integrands

- High-order quadrature assumes smoothness.
- Example:  $\int_{-1}^1 e^{-|x|} dx$  with a single Gauss rule.
- Better: same Gauss rule on 2 subintervals.



- For piecewise constant approximation matrix entries are

$$[\mathbf{C}]_{ij} = \int_{\Delta_i} \int_{\Delta_j} \phi_i(\mathbf{y}) c(\mathbf{x}, \mathbf{y}) \phi_j(\mathbf{x}) d\mathbf{y} d\mathbf{x}$$

- Typical covariance functions have low smoothness for  $\mathbf{x} = \mathbf{y}$ .
- Same trick as in previous example: divide the integration region (subset of  $D \times D$ ) into subregions such that no points with  $\mathbf{x} = \mathbf{y}$  lie in the interior of a subregion.

# Adapted Quadrature

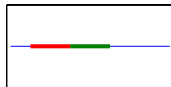
1D RF  $\Rightarrow$  2D integration

- Integration region Cartesian product of intervals  $\Delta_i$  and  $\Delta_j$ .
- Three possible cases for points  $x = y$ :

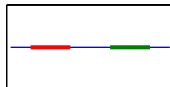
$\Delta_1 = \Delta_2$



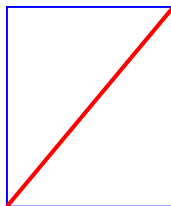
$\Delta_1 \cap \Delta_2$  one point



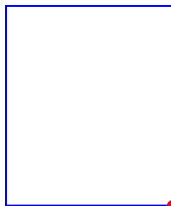
$\Delta_1 \cap \Delta_2$  empty



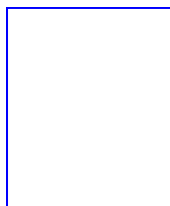
inside



on boundary



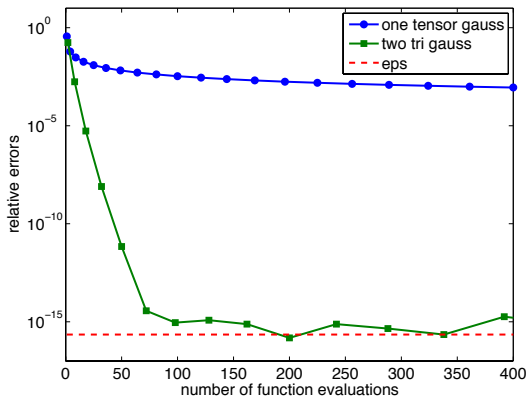
none



# Adapted Quadrature

## Quadrature rule for identical case

- Only need to worry about identical intervals case.
- Subdivision obvious: divide square into two triangles.
- Compare product Gauss quadrature over square with two triangular Gauss formulas over the two triangles:





- Integration region Cartesian product  $\Delta_i \times \Delta_j$  of two triangles
- After transformation of  $\Delta_i$  and  $\Delta_j$  to reference triangle integration domain is fixed.
- Possible cases in 2D:
  - identical triangles
  - common edge
  - common point
  - disjoint

- Similar quadrature problems in 3D-BEM, but there kernels have stronger singularities in  $x = y$ .
- Adapt 3D-BEM quadrature techniques [Sauter & Schwab, 2004]
- Three basic steps::
  - (1) Change of variables to shift singularity to origin.
  - (2) Divide domain of integration leaving singularity on subdomain boundary.
  - (3) Apply standard quadrature on subdomains.
- Consider case of identical triangles.

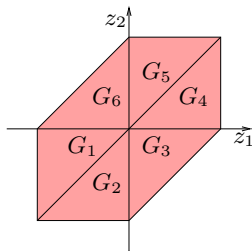
reference triangle:

$$R = \left\{ (x_1, x_2) \in \mathbb{R}^2 : 0 \leq x_1 \leq 1, 0 \leq x_2 \leq x_1 \right\}$$

# Adapted Quadrature

## Identical triangles in 2D

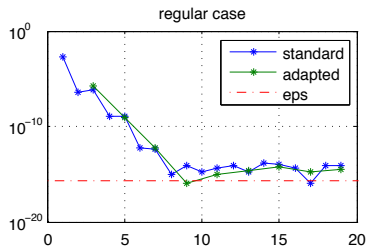
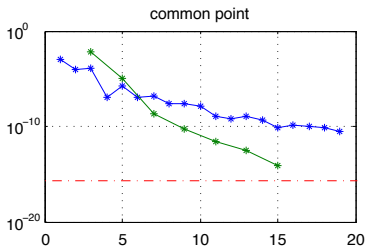
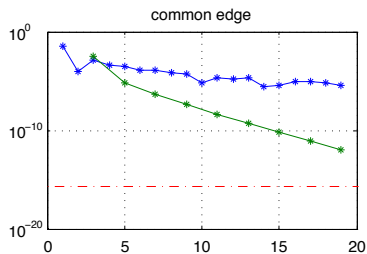
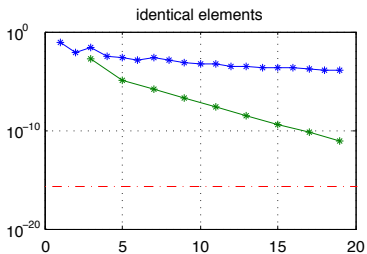
- Reference triangle:  
 $R = \{(x_1, x_2) \in \mathbb{R}^2 : 0 \leq x_1 \leq 1, 0 \leq x_2 \leq x_1\}$
- Difference coordinate  $z = y - x \Rightarrow$  points with  $x = y$  fixed at  $z = 0$ .
- Projection of the domain of integration on the  $z$ -plane



- 6 subdomains (all 4-simplices)  $\Rightarrow$  quadrature rules for 4-simplices or transformation to  $[0, 1]^4$

# Adapted Quadrature

Example:  $c(\mathbf{x}, \mathbf{y}) = \exp(-\|\mathbf{y} - \mathbf{x}\|)$



# Lanczos Eigenpair Approximation

## Solving the generalized eigenvalue problem

- Require  $M$  largest approximate eigenvalues & associated eigenvectors of generalized eigenvalue problem.
- Krylov projection methods avoid computing all eigenpairs; require only matrix-vector products
- Covariance operators selfadjoint, hence short recurrence Krylov methods like Lanczos applicable.
- Thick-Restart variant of Lanczos [Simon & Wu, 2000] allows iterative improvement of desired eigenspace by efficient restarting scheme.
- Extended to generalized eigenvalue problem and block version (multiple eigenvalues)

- Lanczos-decomposition after  $m$  (standard) steps:

$$\mathbf{A}\mathbf{Q}_m = \mathbf{Q}_m\mathbf{T}_m + \beta_m\mathbf{q}_{m+1}\mathbf{e}_m^T \quad (\text{L})$$

- $k < m$  Ritz values  $\vartheta_1, \vartheta_2, \dots, \vartheta_k$  to be refined in next restart cycle
- Ritz pairs  $(\vartheta_j, \mathbf{y}_j)$  satisfy

$$\mathbf{T}_m\mathbf{Y} = \mathbf{Y}\text{diag}(\vartheta_1, \vartheta_2, \dots, \vartheta_k) =: \mathbf{Y}\hat{\mathbf{T}}_k \quad \text{with} \quad \mathbf{Y}^T\mathbf{Y} = \mathbf{I}$$

Multiply (L) from right by  $\mathbf{Y}$

$$\mathbf{A}\hat{\mathbf{Q}}_k = \hat{\mathbf{Q}}_k\hat{\mathbf{T}}_k + \beta_m\hat{\mathbf{q}}_{k+1}\mathbf{s}^T$$

with  $\hat{\mathbf{Q}}_k = \mathbf{Q}_m\mathbf{Y}$ ,  $\hat{\mathbf{q}}_{k+1} = \mathbf{q}_{m+1}$  and  $\mathbf{s} = \mathbf{Y}^T\mathbf{e}_m$

**but:** this is not a Lanczos-decomposition (trailing rank-1 matrix)

- Next Lanczos vector  $\hat{\mathbf{q}}_{k+2}$  by full orthogonalization:

$$\begin{aligned}\hat{\beta}_{k+1} \hat{\mathbf{q}}_{k+2} &= (\mathbf{I} - \hat{\mathbf{Q}}_{k+1} \hat{\mathbf{Q}}_{k+1}^T) \mathbf{A} \hat{\mathbf{q}}_{k+1} \\ &= (\mathbf{I} - \hat{\mathbf{q}}_{k+1} \hat{\mathbf{q}}_{k+1}^T - \hat{\mathbf{Q}}_k \hat{\mathbf{Q}}_k^T) \mathbf{A} \hat{\mathbf{q}}_{k+1} \\ &= \mathbf{A} \hat{\mathbf{q}}_{k+1} - \hat{\alpha}_{k+1} \hat{\mathbf{q}}_{k+1} - \hat{\mathbf{Q}}_k \beta_m \mathbf{s}\end{aligned}$$

- $\hat{\mathbf{Q}}_k^T \mathbf{A} \hat{\mathbf{q}}_{k+1} = \beta_m \mathbf{s}$
- Obtain decomposition with right structure

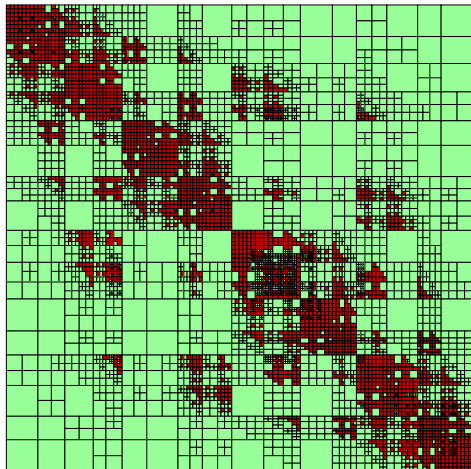
$$\mathbf{A} \hat{\mathbf{Q}}_{k+1} = \hat{\mathbf{Q}}_{k+1} \hat{\mathbf{T}}_{k+1} + \beta_{k+1} \hat{\mathbf{q}}_{k+2} \mathbf{e}_{k+1}^T$$

- Not a proper Lanczos decomposition ( $\hat{\mathbf{T}}_{k+1}$  not tridiagonal), but can now continue with 3-term recurrence.

$$\hat{\mathbf{T}}_{k+1} = \begin{pmatrix} \hat{\mathbf{T}}_k & \beta_m \mathbf{s} \\ \beta_m \mathbf{s}^T & \hat{\alpha}_{k+1} \end{pmatrix}$$

# Hierarchical Matrix Approximation

- Algebraic variant of fast multipole method, [Hackbusch et al., 2000]
- Partition dense matrix into rectangular blocks of 2 types
  - full near-field blocks,
  - low-rank far field blocks
- blocks correspond to clusters of degrees of freedom, i.e., clusters of supports of Galerkin basis functions
- yields data-sparse representation of matrix, construction  $O(N \log N)$ , matrix-vector product in  $O(N)$ .





- If  $\Delta_i$  and  $\Delta_j$  are well separated, the covariance function can be approximated by a low degree interpolation:

$$c(\mathbf{x}, \mathbf{y}) \approx \tilde{c}(\mathbf{x}, \mathbf{y}) = \sum_{k=1}^r c(\mathbf{x}_k, \mathbf{y}) \ell_k(\mathbf{x})$$

- $\ell_k$  are Lagrange polynomials to the interpolation points  $\{\mathbf{x}_k\}_{k=1}^r$
- This is also true for two well-separated clusters  $\sigma$  and  $\tau$  of elements of the triangulation  $\mathcal{T}_h$

- For  $[C]_{ij}$  for triangles  $\Delta_i \in \sigma$  and  $\Delta_j \in \tau$ :

$$\begin{aligned} [C]_{ij} &= \int_{\Delta_i} \int_{\Delta_j} \phi_i(\mathbf{y}) c(\mathbf{x}, \mathbf{y}) \phi_j(\mathbf{x}) d\mathbf{y} d\mathbf{x} \\ &\approx \int_{\Delta_i} \int_{\Delta_j} \phi_i(\mathbf{x}) \left( \sum_{k=1}^r c(\mathbf{x}_k, \mathbf{y}) \ell_k(\mathbf{x}) \right) \phi_j(\mathbf{y}) d\mathbf{y} d\mathbf{x} \\ &= \sum_{k=1}^r \left( \int_{\Delta_i} c(\mathbf{x}_k, \mathbf{y}) \phi_i(\mathbf{y}) d\mathbf{y} \right) \left( \int_{\Delta_j} \ell_k(\mathbf{x}) \phi_j(\mathbf{x}) d\mathbf{x} \right) \\ &= [A_{\sigma, \tau} B_{\tau}]_{ij} \end{aligned}$$

⇒ whole blocks (maybe after permutation of the indices) of  $C$  can be approximated by a rank- $r$  matrix in factored form

- Assembly of hierarchical matrix approximation of  $C$ :
  - (1) Divide triangulation into cluster (cluster tree, clustering strategy, minimal cluster size)
  - (2) Determine for each pair of clusters whether corresponding matrix block can be approximated by a low rank matrix (block cluster tree)
  - (3) admissibility condition for cluster pair  $(\sigma, \tau)$ :

$$\min(\text{diam}(\sigma), \text{diam}(\tau)) \leq \eta \text{dist}(\sigma, \tau)$$

- (4) compute for each matrix block the low rank approximation (admissible) or the full block (inadmissible)
- ⇒ assembly of hierarchical matrix and the matrix-vector-product have complexity of  $O(N \log N)$ .
- ⇒ Lanczos solver for integral operator becomes scalable.

# Hierarchical Matrix Approximation

From  $\mathcal{H}$  to  $\mathcal{H}^2$  matrices

- If clusters well-separated covariance function smooth in  $\mathbf{x}$  and  $\mathbf{y}$
- ⇒ interpolate the covariance function in **both** variables:

$$\begin{aligned} [\mathbf{C}]_{ij} &\approx \sum_{l=1}^r \sum_{k=1}^r \left( \int_{\Delta_i} \ell_l(\mathbf{y}) \phi_i(\mathbf{y}) d\mathbf{y} \right) c(\mathbf{x}_k, \mathbf{y}_l) \left( \int_{\Delta_j} \ell_k(\mathbf{x}) \phi_j(\mathbf{x}) d\mathbf{x} \right) \\ &= [V_\sigma S_{\sigma, \tau} W_\tau]_{ij} \end{aligned}$$

- another admissibility condition:

$$\max(\text{diam}(\sigma), \text{diam}(\tau)) \leq \eta \text{dist}(\sigma, \tau)$$

- Together with certain other techniques ( nested cluster basis)  
matrix-vector product complexity reduced to  $O(N)$

- ① Expansions of Random Fields
  - Random Fields and Covariance
  - RKHS
  - Karhunen-Loève Expansion
- ② Numerical Approximation
  - Galerkin Discretization
  - Adapted Quadrature
  - Lanczos Eigenpair Approximation
  - Hierarchical Matrix Approximation
- ③ Numerical Examples

- Bessel covariance (Matérn family,  $\nu = 1$ ):

$$k_1(\mathbf{x}, \mathbf{y}) = \frac{\|\mathbf{x} - \mathbf{y}\|}{c} K_1 \left( \frac{\|\mathbf{x} - \mathbf{y}\|}{c} \right), \quad \mathbf{x}, \mathbf{y} \in D = [-1, 1]^2.$$

- $\mathcal{U}_n$ : piecewise constants on triangulation of  $D$
- hierarchical matrix parameters

degree of interpolation	: 4
admissibility parameter	: $1/c$
minimal cluster size	: 62

- 5 largest eigenvalues with restart length 10

- **Environment:**

MATLAB 2012a on single node machine,

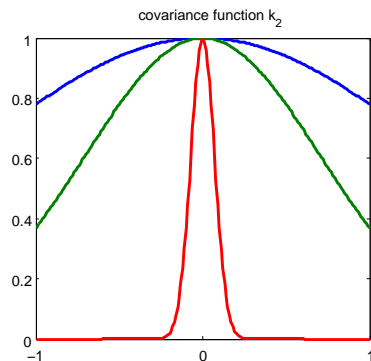
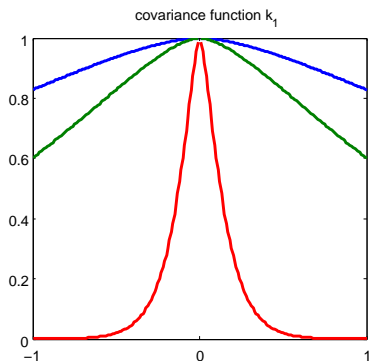
Opteron 6136 (2.4 GHz), 256 GB RAM,

Calls to HLib 1.4 / HLib Pro libraries (MPI Leipzig) via MEX

- Gaussian covariance kernel:

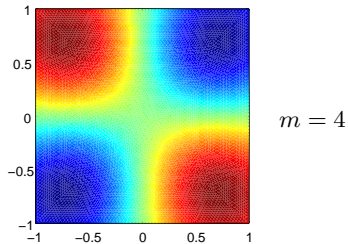
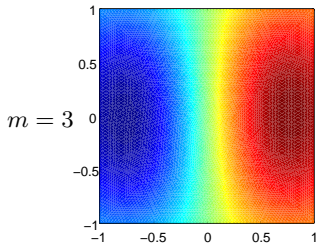
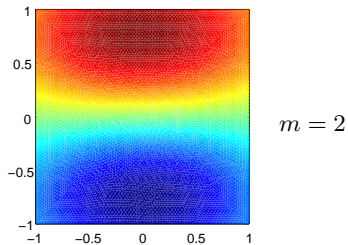
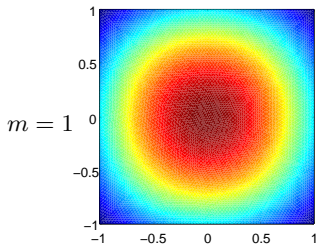
$$k_2(\mathbf{x}, \mathbf{y}) = \exp\left(-\frac{\|\mathbf{x} - \mathbf{y}\|^2}{c^2}\right)$$

- correlation lengths  $c = 0.1, 1, 2$



# Numerical examples

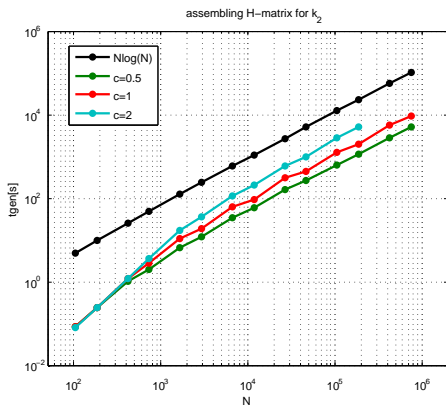
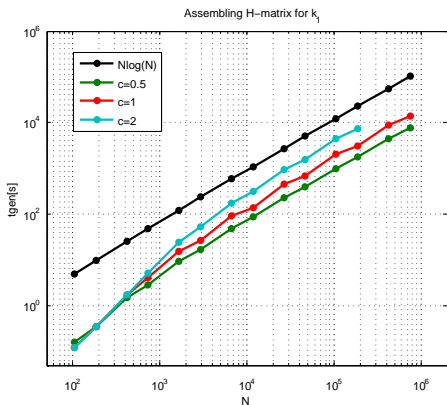
First four eigenmodes  $c = 0.5$





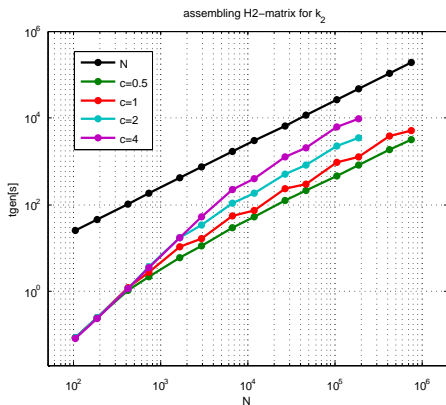
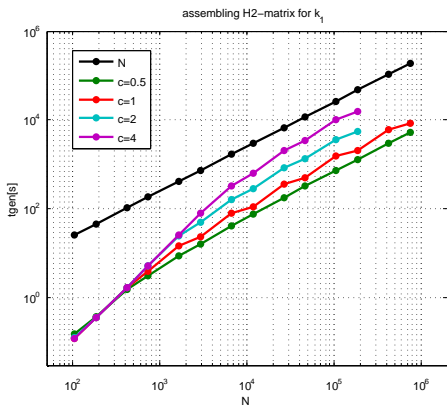
# Numerical examples

## Assembly timings, $\mathcal{H}$ matrices



# Numerical examples

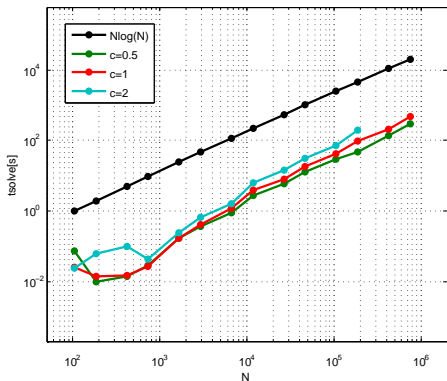
## Assembly timings, $\mathcal{H}^2$ matrices



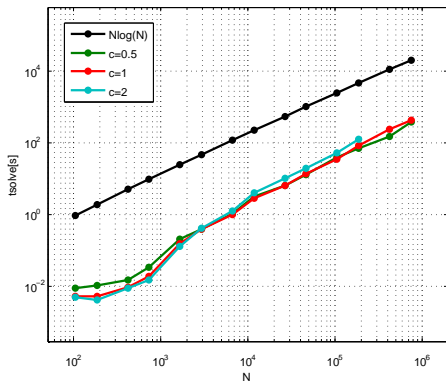
# Numerical examples

## Solution timings, $\mathcal{H}$ matrices

eigenproblem with  $\mathcal{H}$ -matrix for  $k_1$



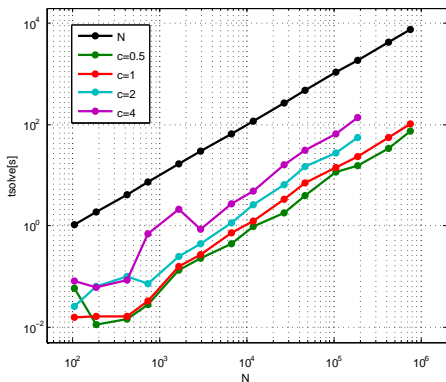
eigenproblem with  $\mathcal{H}$ -matrix for  $k_2$



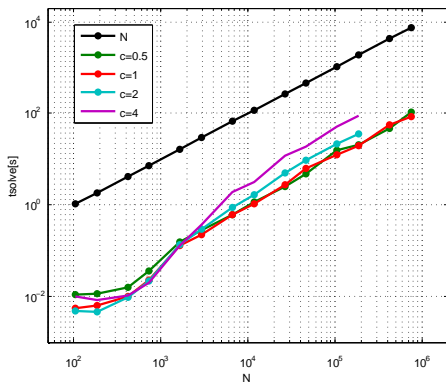
# Numerical examples

## Solution timings, $\mathcal{H}^2$ matrices

eigenproblem with H2-matrix for  $k_1$

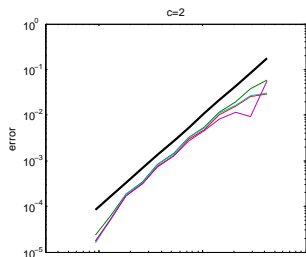
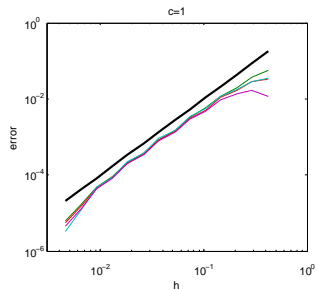
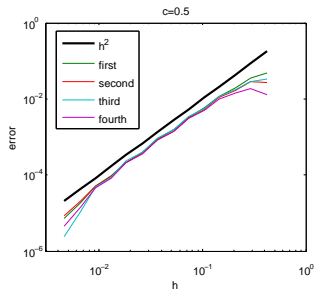


eigenproblem with H2-matrix for  $k_2$



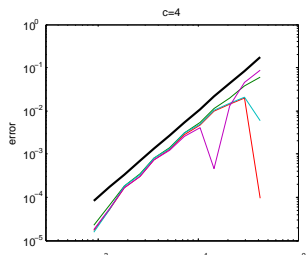
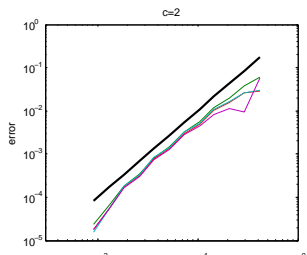
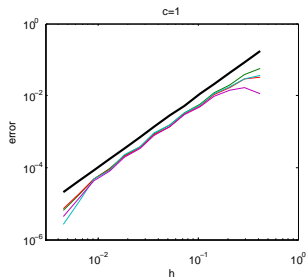
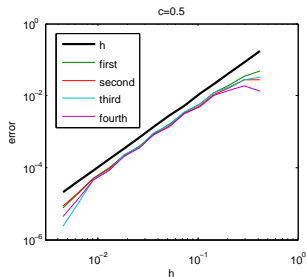
# Numerical examples

## Convergence for $k_1, \mathcal{H}$ matrices



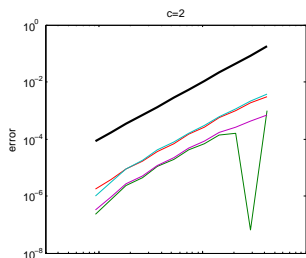
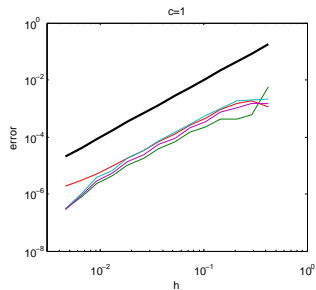
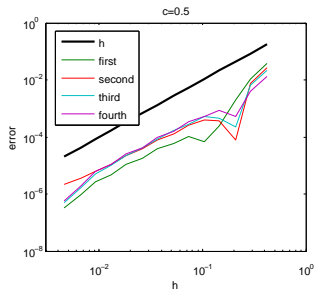
# Numerical examples

## Convergence for $k_1, \mathcal{H}^2$ matrices



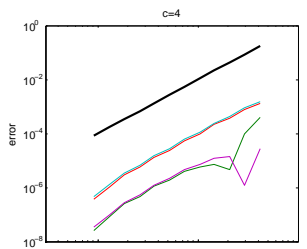
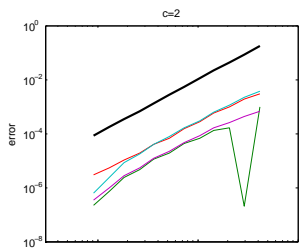
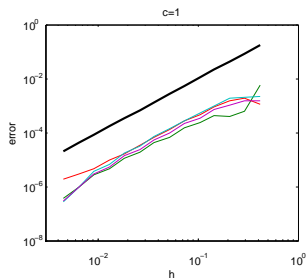
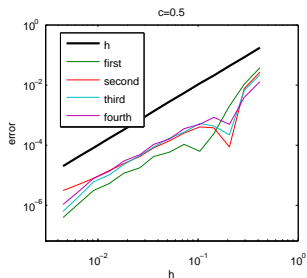
# Numerical examples

## Convergence for $k_2, \mathcal{H}$ matrices



# Numerical examples

## Convergence for $k_2, \mathcal{H}^2$ matrices

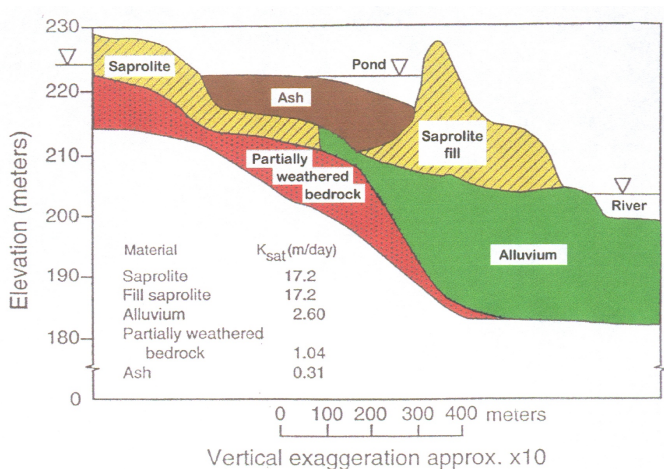




# Numerical examples

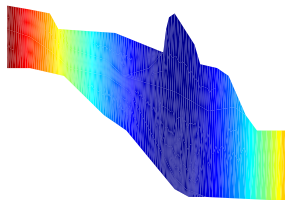
L-site

[Rivière & Wheeler, 1999]

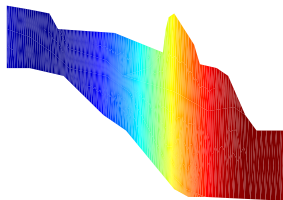


# Numerical examples

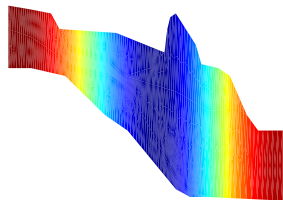
L-site: covariance modes, Bessel correlation,  $\ell = 400m$



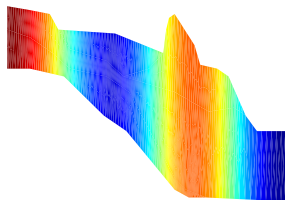
mode 1



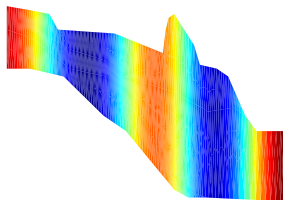
mode 2



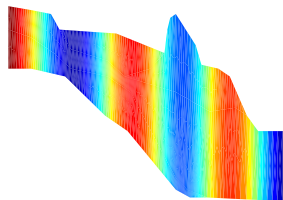
mode 3



mode 4



mode 5



mode 6

## Summary

- Scalable covariance eigenvalue solver based on restarted (block) Lanczos and hierarchical matrix approximation
- Adapted quadrature
- Can incorporate conditioning on measured data, Kriging, REML estimates of mean.
- Flexible w.r.t. kernel, geometry.

## In progress

- 3D (essentially just the quadrature).
- Pcw. linears/quadratics.
- Localized alternatives to KL (joint with Raul Tempone).

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